

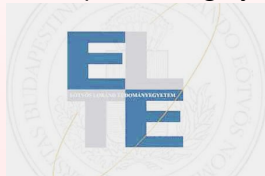
Some new results on node-capacitated packing of \mathcal{A} -paths

Gyula Pap

Egerváry Research Group
www.cs.elte.hu/egres



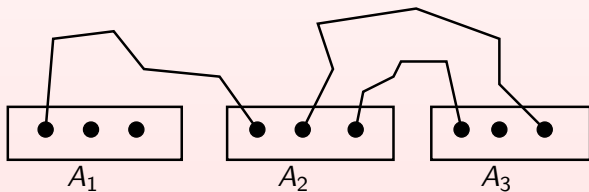
Eötvös University
Budapest, Hungary



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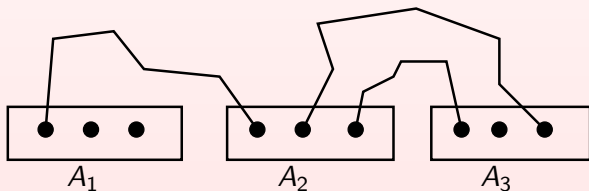
\mathcal{A} -paths — definition

- Let $G = (V, E)$ be an undirected graph.



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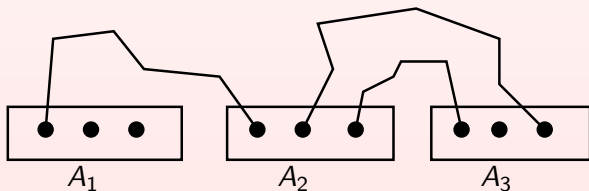
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- Let $\mathcal{A} = \{A_1, \dots, A_k\}$ be a family of disjoint subsets of V , called terminal sets.



\mathcal{A} -paths — definition

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- Let $\mathcal{A} = \{A_1, \dots, A_k\}$ be a family of disjoint subsets of V , called terminal sets.
- Let $A := \bigcup \mathcal{A}$, the set of terminal nodes.

A path in G is called an \mathcal{A} -**path**, if its ends are in two distinct terminal sets.



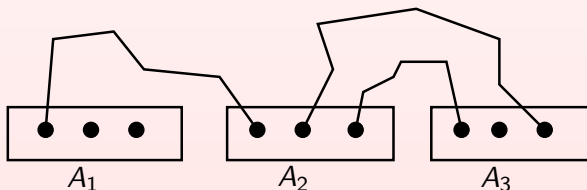
Packing node-disjoint \mathcal{A} -paths

Problem:

- find a maximum number of fully node-disjoint \mathcal{A} -paths
- notation: $\nu(G, \mathcal{A})$

Special cases:

- disjoint $s-t$ paths
- maximum matching
- edge-disjoint \mathcal{A} -paths



Packing disjoint \mathcal{A} -paths

Some earlier results:

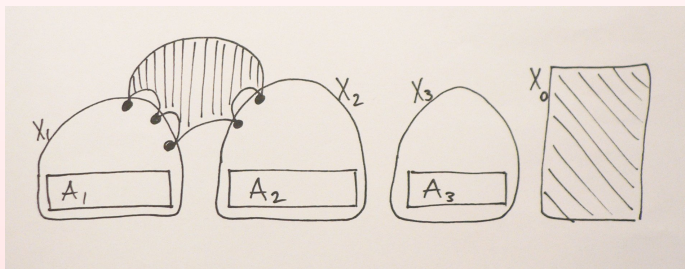
- Gallai, 1961, node-disjoint \mathcal{A} -paths for $\mathcal{A} = \{\{a\} : a \in A\}$
- Lovász, Cherkassky, 1976, min-max formula for edge-disjoint A -paths, assuming the Eulerian property
- Mader, 1978, edge-disjoint \mathcal{A} -paths, min-max formula
- Mader, 1979, node-disjoint \mathcal{A} -paths, min-max formula
- Sebő, Szegő, 2004, structural description
- polytime algorithm: Lovász (1980) + Schrijver (200?)
- generalizations: non-zero A -paths in group-labeled graph (Chudnovsky, Geelen, Gerards, Goddyn, Lohman, Seymour, 2005), non-returning A -paths in permutation-labeled graphs (P, 2006)

Packing node-disjoint \mathcal{A} -paths

Mader's Theorem, 1979

$$\nu(G, \mathcal{A}) = \min |X_0| + \sum_{K \in \text{comp}(G - X_0 - \cup E[X_i])} \left\lfloor \frac{1}{2} |K \cap \cup X_i| \right\rfloor$$

where the minimum is taken over disjoint subsets $X_0, X_1, \dots, X_k \subseteq V$ such that $A_i \subseteq X_0 \cup X_i$ for all i .



Packing \mathcal{A} -paths subject to edge- or node-capacities

Let $b \in \mathbb{N}^V$ (or \mathbb{N}^E) denote the capacities.

b -packing of \mathcal{A} -paths is the following integer programming problem, the optimum value of which is denoted by $\nu_b(G, \mathcal{A})$:

$$\max x \cdot \mathbf{1}$$

$$x : \mathcal{A}\text{-paths} \rightarrow \mathbb{N}$$

$$\sum_{v \in P} x(P) \leq b(v) \quad \text{for all } v \in V \text{ (or } E)$$

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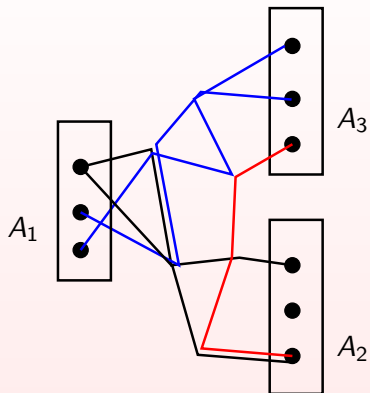
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Theorem

The LP, and its dual admit half-integral optima.

- Integrality gap $3/2$.

Just an ugly b -packing



Mader's Theorem for b -packing of \mathcal{A} -paths

$$\nu(G, \mathcal{A}) = \min b(X_0) + \sum_{K \in \text{comp}'(G - X_0 - \cup E[X_i])} \left\lfloor \frac{1}{2} b(K \cap \cup X_i) \right\rfloor$$

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Special cases:

- maximum flow
- maximum b -matching
- maximum edge-capacitated b -packing of \mathcal{A} -paths

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- maximum fractional b -packing via ellipsoid method
- how to construct a maximum integral b -packing from a maximum fractional b -packing?

Maximum integral flow using Gerards' idea

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- augment value of y one-by-one to reach OPT

Maximum integral flow using Gerards' idea

Proximity Lemma for flows

Let y be an integral flow in G, b . Then the following assertions are equivalent:

- There is an integral flow y' larger than y .
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Corollary

Augmenting an integral flow by one can be performed in strongly polynomial time by a reduction to disjoint s - t -paths.

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Corollary

Given G, s, t, b , we can find a maximum integral s - t -flow in polynomial time.

Maximum b -packing of \mathcal{A} -paths using Gerards' idea

Proximity Lemma for b -packing of \mathcal{A} -paths

Let $(x_{i,j})$ be (the flow-decomposition of) an integral b -packing of \mathcal{A} -paths. Then the following two assertions are equivalent:

- There is an integral b -packing $(x'_{i,j})$ larger than $(x_{i,j})$.
- There is an integral b -packing $(x'_{i,j})$ larger than $(x_{i,j})$ satisfying $x - 2|V|^4 \leq x' \leq x + 2$.

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Corollary

Augmenting an integral b -packing by one can be performed in strongly polynomial time by a reduction to disjoint \mathcal{A} -paths.

Theorem, P, 2006

Given G, \mathcal{A}, b , we can find a maximum integral b -packing of \mathcal{A} -paths in polynomial time.

Matroid Fractional Matching

Consider

- a finite or infinite matroid $\mathcal{M} = (S, \mathcal{I})$
- a finite set \mathcal{E} of lines, i.e. two-ranked flats of \mathcal{M}
- for $K \subseteq S$ we define $d_K \in \{0, 1, 2\}^{\mathcal{E}}$ by

$$d_K(e) := r(K \cap e) \quad \text{for } e \in \mathcal{E}.$$

The **Matroid Fractional Matching Polytope** is defined by

$$\mathcal{P}(\mathcal{M}, \mathcal{E}) := \left\{ x \in \mathbb{R}_+^{\mathcal{E}} : d_K \cdot x \leq r(K) \quad \text{for all } K \subseteq S \right\}.$$

Vande Vate's Formula

The maximum size of a fractional matching:

$$\nu^*(\mathcal{M}, \mathcal{E}) := \max \{ \mathbf{1} \cdot x : x \in \mathcal{P}(\mathcal{M}, \mathcal{E}) \}$$

Theorem (Vande Vate, 1992)

$$\nu^*(\mathcal{M}, \mathcal{E}) = \min \left\{ \frac{1}{2}r(K) + \frac{1}{2}r(L) : \frac{1}{2}d_K + \frac{1}{2}d_L \geq \mathbf{1} \right\}$$

Observation (Gijswijt, 2006)

The above description of the matroid fractional matching polytope is totally dual half-integral.

Application of Matroid Fractional Matching

Lex Schrijver's construction:

- Let l_1, \dots, l_k be distinct 1-dimensional subspaces of \mathbb{R}^2 ,
- for $ab \in E$, $L_{ab} := \{x \in (\mathbb{R}^2)^V : x(a) = x(b), x|_{V-a-b} \equiv 0\}$,
- let $Q := \{x \in (\mathbb{R}^2)^V : x(a) \in l_i \text{ for } a \in A_i, x|_{V-A} \equiv 0\}$,
- $\mathcal{E} := \{L_{ab}/Q : ab \in E\} < \mathcal{Z} := (\mathbb{R}^2)^V/Q$.

Theorem (Lex Schrijver)

$$\nu(G, \mathcal{A}) = \nu(\mathcal{M}_{\mathcal{Z}}, \mathcal{E}) - |V - A|$$

Theorem (P, 2006)

$$\nu^*(G, \mathcal{A}) = \nu^*(\mathcal{M}_{\mathcal{Z}}, \mathcal{E}) - |V - A|$$